****

**Addis Ababa University**

**Addis Ababa Institute of Technology**

**School of Electrical and Computer Engineering**

Project Proposal

Self Driving Car plus Driver Assistance System

Advisors’ Name: Daniel Delibe

By:

Selam Habtom

Biniam Kassahun

Kilet Meshesha

Abstract

Self Driving Car + Driver Assistance System is a system that can be installed on different vehicles to assist the driver of the vehicle to drive well and minimize the risk of road traffic accidents. This risk of road traffic accident can be minimized by making the vehicles self aware and interacting with the environment in accordance.

A number of factors contribute to the risk of collision, including vehicle design, speed of operation, road design, road environment, and driver skill, impairment due to alcohol or drugs, and behavior, notably speeding and racing. Even though the factors are very diversified and difficult to tackle each and every factors, but only by adding abilities to the vehicles to be self aware and interact accordingly, the risk of road traffic accident can be minimized significantly.

**Table of content**

**Introduction and Background**

**Self Driving Car + Driver Assistance System (SDC+DAs)** is a system that can be installed on different vehicles to assist the driver of the vehicle to drive well and minimize the risk of road traffic accidents. This risk of road traffic accident can be minimized by making the vehicles self aware and interacting with the environment in accordance.

The primary purpose of this **SDC+DAs** plus driving assistant system is to make driving become much safer and easier. And the system has a lot to do with a country like Ethiopia. According to the latest WHO data published in may 2014 Road Traffic Accident Deaths in Ethiopia reached 15,015 or 2.50% of total deaths. The age adjusted Death Rate is 20.16 per 100,000 of population ranks Ethiopia #68 in the world. Since the problem related to road traffic accident is so much crucial and needs special attention, building such **SDC+DAs** can significantly reduce the existing road traffic accident that exist in Ethiopia.

Even though it is difficult to fully eradicate every and each road traffic accident using these system, but the system can play a significant role in minimizing the problems. Recent announcements by Google and also by Mercedes and other major automakers indicate the potential for development in this area.

Driverless cars are often discussed as “disruptive technology” with the ability to transform transportation infrastructure, expand access, and deliver benefits to a variety of users.

Driver error is the cause of most of those crashes and after years of technology improvement that provided more assistance to the driver, the driver was taken out of the equation altogether. Now days, back cameras, assisted braking, GPS, and stability control systems come standard in many models and have improved performance and safety.

With technology companies like Google developing their own self-driving technology for use in existing vehicle models, it appears that technology and car manufacturers may work together on SDV development.

**Problem Statement**

As discussed in introduction part earlier, road traffic accident is a critical issue that should be solved soon enough since lots of people dies because of this road traffic accident and also this road traffic accident adds economical loss too. Deaths from traffic accidents are over 1.2 million worldwide every year. And it could be reduced dramatically, especially since more than 80% of accidents involve human error. It is true that, these problems should be solved soon enough, since the disaster is in wide range. Due to these it appears that new technology is needed to fully eradicate the problem.

The other side is, Imagine if everyone could get around easily and safely, regardless of their ability to drive. Since Self Driving Car + Driver Assistance System can lets cars to be easier to drive by and safer. Since this system lets car to know how to drive on the road while minimizing any risk of collision, the driver is easily assisted by the system. Observers have noted that Self Driving Car + Driver Assistance System (SDC+DAs) may change not only the way we drive but also how we use time and how urban landscapes are developed, and people are starting to take notice.

Motivation

Bvffdhhfghdgfh

**Objective**

The primary purpose of this **SDC+DAs** is to make driving become much safer and easier and imagining if everyone could get around easily and safely, regardless of their ability to drive. Since Self Driving Car + Driver Assistance System can lets cars to be easier to drive by and safer.

In order to achieve the points stated above, the **SDC+DAs** has the following objective to be achieved by cars

1. Learn by themselves, how to drive on the road.
2. Understand the road traffic rules and regulations and act in accordance.
3. Be able to predict any risk of road traffic accidents.
4. Minimize the number of the road traffic accidents and also the death counts
5. Minimize the economic loss that happens because of road traffic accidents

**Methodology**

This **SDC+DA system** is going to be implemented first for on toy cars and once it is tested and verified then the system will be implemented on a real car. Even if the project mainly code intensive and most part of the project is software implementation. it seems that the whole project is software implementation. But there is also hardware implementation part.

Most of the software implementation parts are going to be implemented using the python language. Since the system needs real time competition of different machine learning algorithms, computer vision algorithms and some complex mathematical calculation, it is so much important that the development environment should be full of resources, libraries and also the developed software should run fast while using small memory. And the rest parts of the software implementation are going to be held by C. we will use the Pycharm as IDE for python and Atmel Studio for C.

Resource Requirement and Cost Breakdown

Tentative Project Plan